Chapter 9

Subprograms
Chapter 9 Topics

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- Design Issues for Functions
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- User-Defined Overloaded Operators
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Introduction

- Two fundamental abstraction facilities
  - Process abstraction
    - Emphasized from early days
    - Discussed in this chapter
  - Data abstraction
    - Emphasized in the 1980s
    - Discussed at length in Chapter 11
Fundamentals of Subprograms

- Each subprogram has a single entry point
- The calling program is suspended during execution of the called subprogram
- Control always returns to the caller when the called subprogram’s execution terminates
Basic Definitions

• A subprogram definition describes the interface to and the actions of the subprogram abstraction
  – In Python, function definitions are executable; in all other languages, they are non-executable
  – In Ruby, function definitions can appear either in or outside of class definitions. If outside, they are methods of Object. They can be called without an object, like a function
  – In Lua, all functions are anonymous

• A subprogram call is an explicit request that the subprogram be executed

• A subprogram header is the first part of the definition, including the name, the kind of subprogram, and the formal parameters

• The parameter profile (aka signature) of a subprogram is the number, order, and types of its parameters

• The protocol is a subprogram’s parameter profile and, if it is a function, its return type
Basic Definitions (continued)

- Function declarations in C and C++ are often called *prototypes*.
- A *subprogram declaration* provides the protocol, but not the body, of the subprogram.
- A *formal parameter* is a dummy variable listed in the subprogram header and used in the subprogram.
- An *actual parameter* represents a value or address used in the subprogram call statement.
Actual/Formal Parameter Correspondence

• Positional
  – The binding of actual parameters to formal parameters is by position: the first actual parameter is bound to the first formal parameter and so forth
  – Safe and effective

• Keyword
  – The name of the formal parameter to which an actual parameter is to be bound is specified with the actual parameter
  – Advantage: Parameters can appear in any order, thereby avoiding parameter correspondence errors
  – Disadvantage: User must know the formal parameter’s names
Formal Parameter Default Values

- In certain languages (e.g., C++, Python, Ruby, PHP), formal parameters can have default values (if no actual parameter is passed)
  - In C++, default parameters must appear last because parameters are positionally associated (no keyword parameters)

- Variable numbers of parameters
  - C# methods can accept a variable number of parameters as long as they are of the same type—the corresponding formal parameter is an array preceded by `params`

  - In Ruby, the actual parameters are sent as elements of a hash literal and the corresponding formal parameter is preceded by an asterisk.
Variable Numbers of Parameters

(continued)

- In Python, the actual is a list of values and the corresponding formal parameter is a name with an asterisk
Procedures and Functions

• There are two categories of subprograms
  – *Procedures* are collection of statements that define parameterized computations
  
  – *Functions* structurally resemble procedures but are semantically modeled on mathematical functions

  • They are expected to produce no side effects
  • In practice, program functions have side effects
Design Issues for Subprograms

- Are local variables static or dynamic?
- Can subprogram definitions appear in other subprogram definitions?
- What parameter passing methods are provided?
- Are parameter types checked?
- If subprograms can be passed as parameters and subprograms can be nested, what is the referencing environment of a passed subprogram?
- Are functional side effects allowed?
- What types of values can be returned from functions?
- How many values can be returned from functions?
- Can subprograms be overloaded?
- Can subprogram be generic?
- If the language allows nested subprograms, are closures supported?
Local Referencing Environments

- Local variables can be stack–dynamic
  - Advantages
    - Support for recursion
    - Storage for locals is shared among some subprograms
  - Disadvantages
    - Allocation/de-allocation, initialization time
    - Indirect addressing
    - Subprograms cannot be history sensitive

- Local variables can be static
  - Advantages and disadvantages are the opposite of those for stack–dynamic local variables
Local Referencing Environments: Examples

• In most contemporary languages, locals are stack dynamic

• In C–based languages, locals are by default stack dynamic, but can be declared static

• The methods of C++, Java, Python, and C# only have stack dynamic locals
Semantic Models of Parameter Passing

- In mode
- Out mode
- Inout mode
Models of Parameter Passing

![Diagram showing models of parameter passing]

- **Caller**:
  - (sub \((a, b, c)\))
  - **In mode**:
    - a
  - **Out mode**:
    - b
  - **Inout mode**:
    - c

- **Callee**:
  - (procedure \(\text{sub} \ (x, y, z)\))
  - **Call**:
    - x
  - **Return**:
    - y
  - **Call**:
    - z
Conceptual Models of Transfer

- Physically move a value
- Move an access path to a value
Pass-by-Value (In Mode)

- The value of the actual parameter is used to initialize the corresponding formal parameter
  - Normally implemented by copying
  - Can be implemented by transmitting an access path but not recommended (enforcing write protection is not easy)
  - *Disadvantages* (if by physical move): additional storage is required (stored twice) and the actual move can be costly (for large parameters)
  - *Disadvantages* (if by access path method): must write-protect in the called subprogram and accesses cost more (indirect addressing)
Pass–by–Result (Out Mode)

• When a parameter is passed by result, no value is transmitted to the subprogram; the corresponding formal parameter acts as a local variable; its value is transmitted to caller’s actual parameter when control is returned to the caller, by physical move
  – Require extra storage location and copy operation

• Potential problems:
  – \texttt{sub(p1, p1)}; whichever formal parameter is copied back will represent the current value of \texttt{p1}
  – \texttt{sub(list[sub], sub)}; Compute address of \texttt{list[sub]} at the beginning of the subprogram or end?
Pass-by-Value-Result (inout Mode)

• A combination of pass-by-value and pass-by-result
• Sometimes called pass-by-copy
• Formal parameters have local storage
• Disadvantages:
  – Those of pass-by-result
  – Those of pass-by-value
Pass–by–Reference (Inout Mode)

- Pass an access path
- Also called pass–by–sharing
- Advantage: Passing process is efficient (no copying and no duplicated storage)
- Disadvantages
  - Slower accesses (compared to pass–by–value) to formal parameters
  - Potentials for unwanted side effects (collisions)
  - Unwanted aliases (access broadened)

fun(total, total); fun(list[i], list[j]; fun(list[i], i);
Another issue:

Can the passed reference be changed in the called subprogram?

- In C, it is possible

- But in some other languages, such as Pascal and C++, formal parameters that are addresses are implicitly dereferenced, which prevents such changes
Pass-by-Name (Inout Mode)

- By textual substitution
- Formals are bound to an access method at the time of the call, but actual binding to a value or address takes place at the time of a reference or assignment
- Allows flexibility in late binding
- Implementation requires that the referencing environment of the caller is passed with the parameter, so the actual parameter address can be calculated
Implementing Parameter-Passing Methods

• In most languages parameter communication takes place thru the run–time stack
• Pass–by–reference are the simplest to implement; only an address is placed in the stack
Function header: \texttt{void sub(int a, int b, int c, int d)}

Function call in main: \texttt{sub(w, x, y, z)}

(pass \texttt{w} by value, \texttt{x} by result, \texttt{y} by value-result, \texttt{z} by reference)
Parameter Passing Methods of Major Languages

• C
  – Pass-by-value
  – Pass-by-reference is achieved by using pointers as parameters

• C++
  – A special pointer type called reference type for pass-by-reference

• Java
  – All non-object parameters are passed by value
    So, no method can change any of these parameters
  – Object parameters are passed by reference
Parameter Passing Methods of Major Languages (continued)

- **Fortran 95+**
  - Parameters can be declared to be in, out, or inout mode
- **C#**
  - Default method: pass-by-value
  - Pass-by-reference is specified by preceding both a formal parameter and its actual parameter with `ref`
- **PHP**: very similar to C#, except that either the actual or the formal parameter can specify `ref`
- **Swift**: default passing method is by value, but pass-by-reference can be specified by preceding the formal with `inout`
- **Perl**: all actual parameters are implicitly placed in a predefined array named `@_`
- **Python and Ruby** use pass-by-assignment (all data values are objects); the actual is assigned to the formal
Type Checking Parameters

- Considered very important for reliability
- FORTRAN 77 and original C: none
- Pascal and Java: it is always required
- ANSI C and C++: choice is made by the user
  - Prototypes
- Relatively new languages Perl, JavaScript, and PHP do not require type checking
- In Python and Ruby, variables do not have types (objects do), so parameter type checking is not possible
Multidimensional Arrays as Parameters

- If a multidimensional array is passed to a subprogram and the subprogram is separately compiled, the compiler needs to know the declared size of that array to build the storage mapping function.
Multidimensional Arrays as Parameters: C and C++

- Programmer is required to include the declared sizes of all but the first subscript in the actual parameter
- Disallows writing flexible subprograms
- Solution: pass a pointer to the array and the sizes of the dimensions as other parameters; the user must include the storage mapping function in terms of the size parameters
Multidimensional Arrays as Parameters: Java and C#

- Similar to Ada
- Arrays are objects; they are all single-dimensioned, but the elements can be arrays
- Each array inherits a named constant (length in Java, Length in C#) that is set to the length of the array when the array object is created
Design Considerations for Parameter Passing

• Two important considerations
  – Efficiency
  – One-way or two-way data transfer

• But the above considerations are in conflict
  – Good programming suggest limited access to variables, which means one-way whenever possible
  – But pass-by-reference is more efficient to pass structures of significant size
Parameters that are Subprogram Names

• It is sometimes convenient to pass subprogram names as parameters

• Issues:
  1. Are parameter types checked?
  2. What is the correct referencing environment for a subprogram that was sent as a parameter?
Parameters that are Subprogram Names: Referencing Environment

- **Shallow binding**: The environment of the call statement that enacts the passed subprogram
  - Most natural for dynamic-scoped languages
- **Deep binding**: The environment of the definition of the passed subprogram
  - Most natural for static-scoped languages
- **Ad hoc binding**: The environment of the call statement that passed the subprogram
Calling Subprograms Indirectly

• Usually when there are several possible subprograms to be called and the correct one on a particular run of the program is not known until execution (e.g., event handling and GUIs)

• In C and C++, such calls are made through function pointers
In C#, method pointers are implemented as objects called delegates

- A delegate declaration:

```csharp
public delegate int Change(int x);
```

- This delegate type, named `Change`, can be instantiated with any method that takes an `int` parameter and returns an `int` value

A method:  
```
static int fun1(int x) { ... }
```

Instantiate:  
```
Change chgfun1 = new Change(fun1);
```

Can be called with:  
```
chgfun1(12);
```

- A delegate can store more than one address, which is called a multicast delegate
Design Issues for Functions

• Are side effects allowed?
  – Parameters should always be in-mode to reduce side effect (like Ada)

• What types of return values are allowed?
  – Most imperative languages restrict the return types
  – C allows any type except arrays and functions
  – C++ is like C but also allows user-defined types
  – Java and C# methods can return any type (but because methods are not types, they cannot be returned)
  – Python and Ruby treat methods as first-class objects, so they can be returned, as well as any other class
Overloaded Subprograms

• An *overloaded subprogram* is one that has the same name as another subprogram in the same referencing environment
  - Every version of an overloaded subprogram has a unique protocol
• C++, Java, C#, and Ada include predefined overloaded subprograms
• In Ada, the return type of an overloaded function can be used to disambiguate calls (thus two overloaded functions can have the same parameters)
• Ada, Java, C++, and C# allow users to write multiple versions of subprograms with the same name
Generic Subprograms

- A *generic* or *polymorphic* subprogram takes parameters of different types on different activations
- Overloaded subprograms provide *ad hoc* polymorphism
- *Subtype polymorphism* means that a variable of type T can access any object of type T or any type derived from T (OOP languages)
- A subprogram that takes a generic parameter that is used in a type expression that describes the type of the parameters of the subprogram provides *parametric polymorphism*
  - A cheap compile-time substitute for dynamic binding
Generic Subprograms (continued)

- C++
  - Versions of a generic subprogram are created implicitly when the subprogram is named in a call or when its address is taken with the & operator
  - Generic subprograms are preceded by a template clause that lists the generic variables, which can be type names or class names

```cpp
template <class Type>
Type max(Type first, Type second) {
  return first > second ? first : second;
}
```
Generic Subprograms (continued)

• Java 5.0
  – Differences between generics in Java 5.0 and those of C++:
  1. Generic parameters in Java 5.0 must be classes
  2. Java 5.0 generic methods are instantiated just once as truly generic methods
  3. Restrictions can be specified on the range of classes that can be passed to the generic method as generic parameters
  4. Wildcard types of generic parameters
Generic Subprograms (continued)

• Java 5.0 (continued)

```java
public static <T> T doIt(T[] list) { ... }

- The parameter is an array of generic elements
  (T is the name of the type)

- A call:

  doIt<String>(myList);
```

Generic parameters can have bounds:

```java
public static <T extends Comparable> T doIt(T[] list) { ... }
```

The generic type must be of a class that implements the `Comparable` interface
Generic Subprograms (continued)

- Java 5.0 (continued)
  - Wildcard types
    - `Collection<?>` is a wildcard type for collection classes
    ```java
    void printCollection(Collection<?> c) {
        for (Object e: c) {
            System.out.println(e);
        }
    }
    ```
    - Works for any collection class
Generic Subprograms (continued)

• C# 2005
  – Supports generic methods that are similar to those of Java 5.0
  – One difference: actual type parameters in a call can be omitted if the compiler can infer the unspecified type
  – Another – C# 2005 does not support wildcards
Generic Subprograms (continued)

- **F#**
  - Infers a generic type if it cannot determine the type of a parameter or the return type of a function – *automatic generalization*
  - Such types are denoted with an apostrophe and a single letter, e.g., 'a
  - Functions can be defined to have generic parameters
    
    ```fsharp
    let printPair (x: 'a) (y: 'a) =
      printfn "%A %A" x y
    ```
    - %A is a format code for any type
    - These parameters are not type constrained
• F# (continued)
  – If the parameters of a function are used with arithmetic operators, they are type constrained, even if the parameters are specified to be generic
  – Because of type inferencing and the lack of type coercions, F# generic functions are far less useful than those of C++, Java 5.0+, and C# 2005+
User–Defined Overloaded Operators

- Operators can be overloaded in Ada, C++, Python, and Ruby
- A Python example
  ```python
  def __add__(self, second):
      return Complex(self.real + second.real,
                      self.imag + second.imag)
  
  Use: To compute x + y, x.__add__(y)
  ```
Closures

- A closure is a subprogram and the referencing environment where it was defined
  - The referencing environment is needed if the subprogram can be called from any arbitrary place in the program
  - A static-scoped language that does not permit nested subprograms doesn’t need closures
  - Closures are only needed if a subprogram can access variables in nesting scopes and it can be called from anywhere
  - To support closures, an implementation may need to provide unlimited extent to some variables (because a subprogram may access a nonlocal variable that is normally no longer alive)
A JavaScript closure:

```javascript
function makeAdder(x) {
    return function(y) {return x + y;}
}
...
var add10 = makeAdder(10);
var add5 = makeAdder(5);
document.write("add 10 to 20: " + add10(20) + "<br />");
document.write("add 5 to 20: " + add5(20) + "<br />");

- The closure is the anonymous function returned by makeAdder
```
Closures (continued)

- **C#**
  - We can write the same closure in C# using a nested anonymous delegate
  - `Func<int, int>` (the return type) specifies a delegate that takes an `int` as a parameter and returns and `int`

```
static Func<int, int> makeAdder(int x) {
    return delegate(int y) { return x + y; }
}
...
Func<int, int> Add10 = makeAdder(10);
Func<int, int> Add5 = makeAdder(5);
Console.WriteLine("Add 10 to 20: {0}", Add10(20));
Console.WriteLine("Add 5 to 20: {0}", Add5(20));
```
Coroutines

- A *coroutine* is a subprogram that has multiple entries and controls them itself – supported directly in Lua
- Also called *symmetric control*: caller and called coroutines are on a more equal basis
- A coroutine call is named a *resume*
- The first resume of a coroutine is to its beginning, but subsequent calls enter at the point just after the last executed statement in the coroutine
- Coroutines repeatedly resume each other, possibly forever
- Coroutines provide *quasi–concurrent execution* of program units (the coroutines); their execution is interleaved, but not overlapped
Coroutines Illustrated: Possible Execution Controls

![Diagram showing possible execution controls in coroutines]

(a)
Coroutines Illustrated: Possible Execution Controls

(b)
Coroutines Illustrated: Possible Execution Controls with Loops

![Diagram showing coroutine execution with loops and resuming]

- `resume` from master
- First `resume` to `B`
- Subsequent `resume` to `A`
Summary

• A subprogram definition describes the actions represented by the subprogram
• Subprograms can be either functions or procedures
• Local variables in subprograms can be stack–dynamic or static
• Three models of parameter passing: in mode, out mode, and inout mode
• Some languages allow operator overloading
• Subprograms can be generic
• A closure is a subprogram and its ref. environment
• A coroutine is a special subprogram with multiple entries